LIMX DYNAMICS



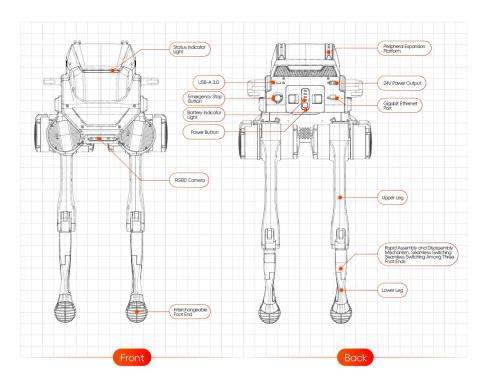
Learn More about Limx Dynamics



Check Tron1's Parameters



Contact Sales











TRONI

LimX TRON1 is a multi-modal biped robot,

which supports innovation in both robotic hardware and software across various disciplines and fields.

With exceptional expandability and locomotion capabilities,

it stands as the most comprehensive all-terrain universal bipedal platform.

POINT-FOOT

SOLE

WHEELED



EASY TO CONTROL IN THE SIMPLEST LEGGED FORM FACTOR

STAND AND WALK IN HUMANOID LEGGED FORM FACTOR

UNLEASH THE FULL POTENTIAL FOR ALL-TERRAIN MOBILITY

"Three-in-One" Modular Foot-end Structure





Movement Speed*: 3m/sLoad Capacity: 10kg

o Climbing Angle*: 30°

All-Terrain

Platform

Universal Mobile

O Battery Life: 2 hours

Obstacle Clearance Height*: 20cm

Seamless Swich Among Point-foot, Support Multi-Modal Algorithm Development

Empower Innovation

Sole, and Wheeled



- Fully Open SDK
- Open Lower-Level Interfaces
- O Support for Mainstream Simulation Platforms: NVIDIA Isaac, MuJoCo, Gazebo, etc.

Spin up RL Research



- Full-process Development in Python
- One-click Sim2Real Deployment
- O Comprehensive and Clear URDF
- O Professional User Manual, Customization Guide, and Code Examples

Multiple Sensors Fusion



- RGBD Camera (Optional)
- Multiple External Interfaces







Voice Interaction Kit



Sensor Expansion Kit

* Climbing angle, obstacle height, and speed data are based on wheel-foot status. The product will undergo continuous optimization, and appearance or configuration may change; please confirm with sales before purchasing. Parameters shown are measured by Limx Dynamics, and actual performance may vary due to environment, usage, device status, and software version.